On the Kaup-Kupershmidt equation. Completeness relations for the squared soutions

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1. Introduction

• Kaup-Kupershmidt equation (KKE)

$$\partial_t f = \partial_{x^5}^5 f + 10f \partial_{x^3}^3 f + 25 \partial_x f \partial_{x^2}^2 f + 20f^2 \partial_x f.$$

• S-integrability of KKE (existence of a Lax representation)

$$\partial_t \mathcal{L} = [\mathcal{L}, \mathcal{A}],$$

$$\mathcal{L} = \partial_{x^3}^3 + 2f\partial_x + \partial_x f,$$

$$\mathcal{A} = 9\partial_{x^5}^5 + 30f\partial_{x^3}^3 + 45\partial_x f\partial_{x^2}^2$$

$$+ (20f^2 + 35\partial_{x^2}^2 f)\partial_x + 10\partial_{x^3}^3 f + 20f\partial_x f.$$

• Factorization of \mathcal{L} operator.

Scalar third order differential operator \Rightarrow matrix first order differential operator

$$\mathcal{L} \to L = i\partial_x + Q - \lambda J,$$

where

$$Q = \begin{pmatrix} \tilde{Q} & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -\tilde{Q} \end{pmatrix}, \qquad J = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}.$$

Lax operator assoc. with $\mathfrak{sl}(3,\mathbb{C})$ with a \mathbb{Z}_3 reduction.

2. Some necessary facts about Lie algebras and the Inverse scattering method

2.1. The $\mathfrak{sl}(r+1,\mathbb{C})$ algebra

• Definition of $\mathfrak{sl}(r+1,\mathbb{C})$

$$A \in \mathfrak{sl}(r+1,\mathbb{C}) \Leftrightarrow \operatorname{tr} A = 0.$$

• Cartan subalgebra $\mathfrak{h} \subset \mathfrak{g}$ — maximal commutative subalgebra. For $\mathfrak{sl}(r+1,\mathbb{C})$ the Cartan basis of \mathfrak{h} reads

$$H_k = E_{kk} - \frac{1}{r+1} \sum_{j=1}^{r+1} E_{jj}, \qquad k = 1, \dots, r.$$

• Root system Δ of \mathfrak{g} contains all covectors α that

$$[H_k, E_\alpha] = \alpha(H_k) E_\alpha,$$

where $\alpha \in \mathfrak{h}^*$ is a root and $E_{\alpha} \in \mathfrak{g}$ is the corresponding root vector. For $\mathfrak{sl}(r+1)$ the roots can be presented by

$$e_i - e_j, \quad i \neq j, \quad i, j = 1, \dots, r+1,$$

where $\{e_k\}_{k=1}^r$ is an orthonormal basis in the Euclidean space \mathbb{E}^r . The set of all simple roots is formed by

$$\alpha_j = e_j - e_{j+1},$$

while the maximal root is

$$\alpha_{\max} = e_1 - e_{r+1}.$$

• The Weyl basis of $\mathfrak{sl}(r+1)$ reads

$$E_{e_j-e_j} = E_{ij}, \quad (E_{ij})_{mn} = \delta_{im}\delta_{jn}.$$

We require that H_j and E_{α} are normalized with respect to Killing form, i.e.

• The second Casimir operator P which has the important property

$$P(A \otimes B) = (B \otimes A)P, \qquad \forall A, B \in SL(r+1)$$

looks as follows

$$P = \sum_{j=1}^{r} H_j \otimes H_j + \sum_{\alpha \in \Delta} E_\alpha \otimes E_{-\alpha}.$$

2.2. Spectral problem for L operator

• Generalized Zakharov-Shabat system

$$L\psi = (i\partial_x + Q - \lambda J)\psi = 0,$$

where $Q(x), J \in \mathfrak{g}$ (without loss of generality J can be chosen as a Cartan element while Q(x) is a linear combinations the Weyl generators of \mathfrak{g}) and $\psi(x,\lambda) \in G$. In the simplest case of zero boundary conditions, i.e. $\lim_{x\to\pm\infty} Q(x) = 0$ the continuous part of the spectrum of L fills up the \mathbb{R} -axis of the complex λ -plane.

• The scattering (data) matrix

$$T(\lambda) = \hat{\psi}_+(x,\lambda)\psi_-(x,\lambda), \qquad \lambda \in \mathbb{R},$$

where $\psi_{\pm}(x,\lambda)$ are Jost solutions to fulfill

$$\lim_{x \to \pm \infty} \psi_{\pm}(x,\lambda) e^{i\lambda Jx} = \mathbb{1}.$$

There exist fundamental solutions $\chi^+(x,\lambda)$ and $\chi^-(x,\lambda)$ which possess analitical properties in \mathbb{C}_+ and \mathbb{C}_- . $\chi^+(x,\lambda)$ and $\chi^-(x,\lambda)$ are interrelated via

$$\chi^{+}(x,\lambda) = \chi^{-}(x,\lambda)G(\lambda), \qquad \lambda \in \mathbb{R},$$
$$G(\lambda) = \begin{cases} \hat{S}^{-}(\lambda)S^{+}(\lambda), \\ \hat{D}^{-}(\lambda)\hat{T}^{+}(\lambda)T^{-}(\lambda)D(\lambda). \end{cases}$$

 $S^{\pm}(\lambda), T^{\pm}(\lambda)$ and $D^{\pm}(\lambda)$ are factors in the Gauss decomposition of $T(\lambda)$

$$T(\lambda) = \begin{cases} T^{-}(\lambda)D^{+}(\lambda)\hat{S}^{+}(\lambda), \\ T^{+}(\lambda)D^{-}(\lambda)\hat{S}^{-}(\lambda). \end{cases}$$

2.3. Algebraic reductions

• Reduction group

Let G_R be a discrete group acting on the set fundamental solutions $\{\psi(x,\lambda)\}$ as follows

$$C\psi(x,\kappa(\lambda))C^{-1} = \tilde{\psi}(x,\lambda).$$

The requirement of G_R -invariance of the lin. problem yields to the following conditions

$$CQ(x)C^{-1} = Q(x), \qquad \kappa(\lambda)CJC^{-1} = \lambda J.$$

• Coxeter type reduction

$$\kappa : \lambda \to \omega \lambda, \qquad \omega = e^{2i\pi/h},$$

 $C = \exp(\sum_k \omega^k H_k).$

Consequently Q(x) and J have the form

$$Q = \sum_{k=1}^{r} Q_k H_k, \qquad J = \sum_{\alpha \in A} E_\alpha,$$

where A stands for the set of all admissible roots (simple + minimal roots) of \mathfrak{g} . Thus KKE can be related to a \mathbb{Z}_3 -reduced L operator assoc. with the $\mathfrak{sl}(3)$ algebra.

2.4. Spectral problem for L and Coxeter type reductions

The presence of a Coxeter reduction affects the spectral properties of L — its continuous spectrum consists of a bunch of 2h rays l_{ν} closing equal angles π/h . From now on we shall consider L operator assoc. with the $\mathfrak{sl}(3)$ algebra with a \mathbb{Z}_3 reduction. Each ray l_{ν} is connected with a $\mathfrak{sl}(2)$ subalgebra— the algebra $\{E_{\alpha}, E_{-\alpha}, H_{\alpha}\}$ generated by the root α to fulfill the condition

$$\delta_{\nu} \equiv \{ \alpha \in \Delta | \operatorname{im} \lambda \alpha(J) = 0, \forall \lambda \in l_{\nu} \}, \quad \nu = 1, \dots, 6.$$

The following relations between these root subsystems hold true

$$\delta_{\nu} = \delta_{\nu+3}, \qquad \Delta = \bigcup_{\nu=1}^{3} \delta_{\nu}.$$

The λ -plane splits into 6 domains Ω_{ν} separ. by l_{ν} . One can introduce ordering in Ω_{ν}

$$\Delta_{\nu}^{+} \equiv \{ \alpha \in \Delta | \operatorname{Im} \lambda \alpha(J) > 0, \ \forall \lambda \in \Omega_{\nu} \}, \\ \Delta_{\nu}^{-} \equiv \{ \alpha \in \Delta | \operatorname{Im} \lambda \alpha(J) < 0, \ \forall \lambda \in \Omega_{\nu} \}$$

We shall use the notation $\delta_{\nu}^{\pm} = \Delta_{\nu}^{\pm} \cap \delta_{\nu}$ as well. One can easily see that the following symmetries hold

$$\Delta_{\nu+3}^{\pm} = \Delta_{\nu}^{\mp}, \qquad \delta_{\nu+3}^{\pm} = \delta_{\nu}^{\mp}.$$

In each Ω_{ν} exists a FAS $\chi^{\nu}(x,\lambda)$ in such a way that

$$\chi^{\nu}(x,\lambda) = \chi^{\nu-1}(x,\lambda)G^{\nu}(\lambda), \qquad \lambda \in l_{\nu},$$
$$G^{\nu}(\lambda) = \begin{cases} \hat{S}_{\nu}^{-}(\lambda)S_{\nu}^{+}(\lambda)\\ \hat{D}_{\nu}^{-}(\lambda)\hat{T}_{\nu}^{+}(\lambda)T_{\nu}^{-}(\lambda)D_{\nu}^{+}(\lambda). \end{cases}$$



Figure 1: The contours of integration $\gamma_{\nu} = l_{\nu-1} \cup C_{\nu-1} \cup l_{\nu}$.

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3. Completeness relations for squared solutions of a \mathbb{Z}_3 reduced scattering problem related to the algebra $\mathfrak{sl}(3,\mathbb{C})$

• Squared solutions (eigenfunctions) are introduced by

$$e_{\alpha}^{(\nu)}(x,\lambda) = P_J(\chi^{\nu} E_{\alpha} \hat{\chi}^{\nu}(x,\lambda)),$$

$$h_j^{(\nu)}(x,\lambda) = P_J(\chi^{\nu} H_j \hat{\chi}^{\nu}(x,\lambda)),$$

where P_J stands for the projection which maps onto $\mathfrak{sl}(3)/\mathfrak{h}$. They originate from the Wronskian relations, for example

$$(\hat{\chi}^{\nu}J\chi^{\nu}(x,\lambda)-J)|_{-\infty}^{\infty} = \int_{-\infty}^{\infty} dx \hat{\chi}^{\nu}[J,Q(x)]\chi^{\nu}(x,\lambda)$$

The next theorem represents our main result:

Theorem 1 The squared solutions form a complete set with the following completeness relations

$$\delta(x-y)\Pi = \frac{1}{2\pi} \sum_{\nu=1}^{6} (-1)^{\nu+1} \int_{l_{\nu}} d\lambda \left(G_{\beta_{\nu}}^{(\nu)}(x,y,\lambda) - G_{-\beta_{\nu}}^{(\nu-1)}(x,y,\lambda) \right) - i \sum_{\nu=1}^{6} \sum_{n_{\nu}} \mathop{Res}_{\lambda=\lambda_{n_{\nu}}} G^{(\nu)}(x,y,\lambda).$$

where

$$G_{\beta_{\nu}}^{(\nu)}(x,y,\lambda) = e_{\beta_{\nu}}^{(\nu)}(x,\lambda) \otimes e_{-\beta_{\nu}}^{(\nu)}(y,\lambda),$$
$$\Pi = \sum_{\alpha \in \Delta^{+}} \frac{E_{\alpha} \wedge E_{-\alpha}}{\alpha(J)}.$$

Proof: The completeness relations can be derived starting from the expression

$$\mathcal{J}(x,y) = \sum_{\nu=1}^{6} (-1)^{\nu+1} \oint_{\gamma_{\nu}} G^{(\nu)}(x,y,\lambda) d\lambda.$$

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The Green functions $G^{(\nu)}(x, y, \lambda)$ have the form

$$G^{(\nu)}(x,y,\lambda) = \theta(y-x) \sum_{\alpha \in \Delta_{\nu}^{+}} e_{\alpha}^{(\nu)}(x,\lambda) \otimes e_{-\alpha}^{(\nu)}(y,\lambda)$$
$$-\theta(x-y) \left[\sum_{\alpha \in \Delta_{\nu}^{-}} e_{\alpha}^{(\nu)}(x,\lambda) \otimes e_{-\alpha}^{(\nu)}(y,\lambda) + \sum_{j=1}^{2} h_{j}^{(\nu)}(x,\lambda) \otimes h_{j}^{(\nu)}(y,\lambda) \right]$$

The proof can be done in three steps

1. Lemma 1 The following equality holds for $\lambda \in l_{\nu}$

$$\sum_{\alpha \in \Delta} e_{\alpha}^{(\nu-1)}(x,\lambda) \otimes e_{-\alpha}^{(\nu-1)}(y,\lambda) + \sum_{j=1,2} h_j^{(\nu-1)}(x,\lambda) \otimes h_j^{(\nu-1)}(y,\lambda)$$
$$= \sum_{\alpha \in \Delta} e_{\alpha}^{(\nu)}(x,\lambda) \otimes e_{-\alpha}^{(\nu)}(y,\lambda) + \sum_{j=1,2} h_j^{(\nu)}(x,\lambda) \otimes h_j^{(\nu)}(y,\lambda).$$

According to Cauchy's residue theorem we have

$$\mathcal{J}(x,y) = 2\pi i \sum_{\nu=1}^{6} \sum_{n_{\nu}} \operatorname{Res}_{\lambda=\lambda_{n_{\nu}}} G^{(\nu)}(x,y,\lambda).$$

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In the simplest case when $e_{\alpha}^{(\nu)}(x,\lambda)$ and $h_{j}^{(\nu)}(x,\lambda)$ possess only a single simple pole $\lambda_{\nu} \in \Omega_{\nu}$, i.e.

$$e_{\alpha}^{(\nu)}(x,\lambda) \approx \frac{e_{\alpha,n_{\nu}}^{(\nu)}(x)}{\lambda - \lambda_{n_{\nu}}} + \dot{e}_{\alpha}^{(\nu)}(x) + O(\lambda - \lambda_{n_{\nu}})$$
$$h_{j}^{(\nu)}(x,\lambda) \approx \frac{h_{j}^{(\nu)}(x)}{\lambda - \lambda_{n_{\nu}}} + \dot{h}_{j}^{(\nu)}(x) + O(\lambda - \lambda_{n_{\nu}}).$$

2. Lemma 2 Residues of $G^{(\nu)}(x, y, \lambda)$ are given by

$$\operatorname{Res}_{\lambda=\lambda_{n_{\nu}}} G^{(\nu)}(x,y,\lambda) = \dot{e}_{\beta_{\nu},n}^{(\nu)}(x) \otimes e_{-\beta_{\nu},n}^{(\nu)}(y) + e_{\beta_{\nu},n}^{(\nu)}(x) \otimes \dot{e}_{-\beta_{\nu},n}^{(\nu)}(y).$$

Taking into account the orientation of the contours γ_{ν} we have

$$\mathcal{J}(x,y) = \sum_{\nu=1}^{6} (-1)^{\nu+1} \int_{l_{\nu}} (G^{(\nu)}(x,y,\lambda) - G^{(\nu-1)}(x,y,\lambda)) d\lambda + \sum_{\nu=1}^{6} (-1)^{\nu+1} \int_{C_{\nu}} G^{(\nu)}(x,y,\lambda) d\lambda.$$

3. Lemma 3 In the integrals along the rays contribute only terms related to the roots that belong to δ_{ν}^+ and δ_{ν}^- respectively, i.e.

$$G^{(\nu)}(x,y,\lambda) - G^{(\nu-1)}(x,y,\lambda)$$

= $e^{(\nu)}_{\beta_{\nu}}(x,\lambda) \otimes e^{(\nu)}_{-\beta_{\nu}}(y,\lambda) - e^{(\nu-1)}_{-\beta_{\nu}}(x,\lambda) \otimes e^{(\nu-1)}_{\beta_{\nu}}(y,\lambda).$

Asymptotically $G^{(\nu)}(x, y, \lambda)$ is an entire function hence we are allowed to deform the arcs C_{ν} into $\bar{l}_{\nu} \cup \bar{l}_{\nu+1}$. Thus for the integrals along the arcs C_{ν} one obtains

$$\sum_{\nu=1}^{6} (-1)^{\nu+1} \int_{C_{\nu}} G^{(\nu)}(x,y,\lambda) d\lambda = 2\pi \delta(x-y) \sum_{\alpha \in \Delta^+} \frac{(E_{\alpha} \wedge E_{-\alpha})}{\alpha(J)}.$$

Importance of the completeness relations of the squared solutions.
 Completeness of the squared solutions ⇔ a basis in a functional space.

$$X(x) = \frac{1}{2\pi} \sum_{\nu=1}^{6} (-1)^{\nu+1} \int_{l_{\nu}} d\lambda \left(X_{\beta_{\nu}} e_{\beta_{\nu}}^{(\nu)}(x,\lambda) - X_{-\beta_{\nu}} e_{-\beta_{\nu}}^{(\nu-1)}(x,\lambda) \right) - i \sum_{\nu=1}^{6} X_{\nu}.$$